

### **AMENDMENTS TO THE SPECIFICATION**

Please replace the paragraph beginning on line 20 of page 14 of the specification with the following amended paragraph:

The Y-axis moving mechanism 31 and the Z-axis moving mechanism 32 respectively moves an end effector 41, mentioned later, in two axial directions (Y-axis direction and Z-axis direction in FIG. 1) perpendicular to the aforesaid predetermined conveying direction in each process to adjust (positioning) the relative position between the end effector 41 and the workpiece 2 or a part 3 to be mounted in this workpiece 2. As the Y-axis moving mechanism 31, for example, there is used a Y-axis two-point positioning mechanism comprising a two-point cylinder or a multi-point robot, a Y-axis multi-point positioning mechanism, a Y-axis one-point positioning mechanism, or the like, and as the Z-axis moving mechanism 32, for example, there is used a Z-axis two-point positioning mechanism comprising a two-point cylinder or a multi-point robot, or the like.

Please replace the paragraph beginning on line 9 of page 15 of the specification and replace it with the following amended paragraph:

The aligner mechanism 33 is for adjusting a horizontal position (position in an X-Y plane) of a workpiece 2/part 3 to be introduced into a manufacturing line by the end effector 41, mentioned later, or a workpiece 2 taken out from the manufacturing line by the end effector 41. As this aligner mechanism 33, for example, there is used an X-Y precision stage, an X-Y rotational precision stage, an automatic recognition correction stage, or the like.